Drone Control Experiment

**Research Question:** How does descending haptic guidance effect the learning of drone control with respect to constant guidance or no guidance?

**Experiment setup (between subject)**

2 trails without guidance

6 trails with no / descending / total guidance

2 trails without guidance

**Evaluation metrics** (learning curves per metric)

* Completion time in seconds
* Collision count
* Path length in meters

To do:

* Tune environment so it is not too hard/easy
* Fix time metric
* Fix guidance
* Set right scale for guidance